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LETTER TO THE EDITOR

**On the Kac–Moody algebra of symmetries for a  $\kappa$ dv equation in three dimensions**

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**Abstract.** We have obtained the four different classes of symmetries for the equation

$$p_t + \partial_u^3 p + \partial_v^3 p - 3\partial_u(p\partial_u\partial_v^{-1}p) - 3\partial_v(p\partial_v\partial_u^{-1}p) = 0$$

which is an analogue of the  $\kappa$ dv equation in three spacetime dimensions. Of these four types of symmetries, two depend explicitly on the coordinates. It is then demonstrated that these generators of symmetries close on an infinite-dimensional Kac–Moody algebra.

One of the fundamental problems associated with a given nonlinear evolution equation (NEE) exactly solved by the inverse scattering transform is to construct the hierarchies of equations which have similar properties. The problem of finding an infinite number of Lie–Bäcklund symmetries is also related to it [1]. Exhaustive studies already exist for such properties of integrable two-dimensional systems [2]. Some properties of the three-dimensional  $\kappa$ P equation are also well known [3]. But recent studies by Boiti *et al* [4] have produced many more integrable nonlinear systems in three dimensions. In this letter we follow the approach of admissible Lax operators to deduce the structure of an infinite class of symmetries for an equation which is a straightforward extension of the usual  $\kappa$ dv equation to three dimensions. Four classes of symmetries are obtained of which two depend explicitly on the spacetime coordinates. Finally we show that these symmetries close on an infinite-dimensional Lie algebra.

The nonlinear equation under consideration can be written as

$$p_t + \partial_u^3 p + \partial_v^3 p - 3\partial_u(p\partial_u\partial_v^{-1}p) - 3\partial_v(p\partial_v\partial_u^{-1}p) = 0. \tag{1}$$

It was demonstrated in [4] that the Lax operator associated with (1) is

$$L = \partial_u\partial_v - p \tag{2}$$

where the time evolution is given by

$$\psi_t = A\psi \tag{3}$$

$A$  being an operator depending on  $(\partial_u, \partial_v)$  and also on  $(p, u$  and  $v)$ . We call a class of operators  $A_k$  Lax admissible if

$$[L, A_k] = a_k \tag{4}$$

where  $a_k$  is a multiplication operator only. An important point to note is that in our case  $[L, A_k]$  is to be computed on the eigenspace of  $L\psi = 0$ . In the following we reproduce some such operators and their corresponding multiplication operator  $a_k$ :

$$\begin{aligned} (a) \quad & A_1 = \partial_u; \quad a_1 = p_u \\ (b) \quad & B_1 = u\partial_u; \quad b_1 = p + up_u \end{aligned} \tag{5}$$

$$(c) \quad C_1 = \partial_v; \quad c_1 = p_v$$

$$(d) \quad D_1 = v\partial_v; \quad d_1 = p + vp_v$$

$$\begin{aligned} (e) \quad & A_3 = \partial_u^3 - 3(\partial_v^{-1}p_u)\partial_u \\ & a_3 = p_{3u} - 3p_u(\partial_v^{-1}p_u) - 3p(\partial_v^{-1}p_{2u}) \end{aligned}$$

$$\begin{aligned} (f) \quad & B_3 = u\partial_u^3 + \partial_u^2 - \{3u\partial_v^{-1}p_u + \partial_v^{-1}p\}\partial_u \\ & b_3 = 2p_{2u} + up_{3u} - 4p(\partial_v^{-1}p_u) - 3up(\partial_v^{-1}p_{2u}) - 3up_u(\partial_v^{-1}p_u) - p_u(\partial_v^{-1}p) \end{aligned}$$

$$\begin{aligned} (g) \quad & C_3 = \partial_v^3 - 3(\partial_u^{-1}p_v)\partial_v \\ & c_3 = p_{3v} - 3p_v(\partial_u^{-1}p_v) - 3p(\partial_u^{-1}p_{2v}) \end{aligned}$$

$$\begin{aligned} (h) \quad & D_3 = v\partial_v^3 + \partial_v^2 - \{3v\partial_u^{-1}p_v + \partial_u^{-1}p\}\partial_v \\ & d_3 = 2p_{2v} + vp_{3v} - 4p(\partial_u^{-1}p_v) - 3vp(\partial_u^{-1}p_{2v}) - 3vp_v(\partial_u^{-1}p_v) - p_v(\partial_u^{-1}p) \end{aligned} \tag{6}$$

$$\begin{aligned} (i) \quad & A_5 = \partial_u^5 - 5(\partial_v^{-1}p_u)\partial_u^3 - 5(\partial_v^{-1}p_{2u})\partial_u^2 \\ & \quad + [15\partial_v^{-1}\{p_u(\partial_v^{-1}p_u)\} - 5(\partial_v^{-1}p_{3u}) + 5\partial_v^{-1}\{p(\partial_v^{-1}p_{2u})\}]\partial_u \\ & a_5 = p_{5u} - 5p_{3u}(\partial_v^{-1}p_u) - 10p_{2u}\partial_v^{-1}p_{2u} - 10p_u\partial_v^{-1}p_{3u} + 5p_u \\ & \quad \times \partial_v^{-1}\{p\partial_v^{-1}p_{2u}\} + 15p_u\partial_v^{-1}\{p_u\partial_v^{-1}p_u\} - 5p(\partial_v^{-1}p_{4u}) \\ & \quad + 20p\partial_v^{-1}\{p_u\partial_v^{-1}p_{2u}\} + 5p\partial_v^{-1}\{p\partial_v^{-1}p_{3u}\} + 15\partial_v^{-1}\{p_{2u}\partial_v^{-1}p_u\} \end{aligned}$$

and it is possible to go on and obtain higher-order operators. At this stage an important observation can be made. Let us define the commutators of two such operators  $A_i, B_j$  via the following rule [5]:

$$[[A_i, B_j]] = A'_i[b_j] - B'_j[a_i] + [A_i, B_j] \tag{7}$$

where  $A'_i[b_j]$  denote the Frechet derivative of  $A_i$  in the direction  $b_j$ :

$$A'_i(b_j) = \frac{\partial}{\partial \epsilon} A_i[p + \epsilon b_j]|_{\epsilon=0} \tag{8}$$

and  $A_i, B_j$  denotes the usual commutator in the sense of vector fields. If we now compute  $[[A_3, B_3]]$  then the result turns out to be  $3A_5$ , whence

$$[[A_3, B_3]] = 3A_5 \tag{9}$$

and we generate the higher-order operator  $A_5$ . Furthermore;

$$[[A_5, B_3]] = 5A_7 \quad \text{and so on.} \tag{10}$$

Therefore we call  $B_3$  (as well as  $D_3$ ) the generating Lax operators, and we have a recursive way of determining these higher-order operators. We note some simple commutation rules of such operators:

$$\begin{aligned}
 \llbracket A_1, B_3 \rrbracket &= A_3 & \llbracket A_3, B_1 \rrbracket &= 3A_3 \\
 \llbracket A_1, B_1 \rrbracket &= A_1 & \llbracket B_1, D_1 \rrbracket &= 0 \\
 \llbracket B_1, B_3 \rrbracket &= -3B_3 & \llbracket B_1, D_3 \rrbracket &= 0 \\
 \llbracket C_1, D_3 \rrbracket &= C_3 & \llbracket C_3, D_3 \rrbracket &= 3C_3 \quad \text{etc.}
 \end{aligned} \tag{11}$$

We note that equation (1) results due to the time evolution of  $\psi$  generated by  $A_3 + C_3$ .

Let us now suppose that  $p$  undergo a transformation  $p \rightarrow p + \varepsilon\eta$ , then  $\eta$  satisfies the linearized equation

$$\eta_t + \partial_u^3 \eta + \partial_v^3 \eta - 3\partial_u(\eta \partial_u \partial_v^{-1} p) - 3\partial_u(p \partial_u \partial_v^{-1}) - 3\partial_v(\eta \partial_v \partial_u^{-1} p) - 3\partial_v(p \partial_v \partial_u^{-1}) = 0. \tag{12}$$

Straightforward but laborious computation shows that the solutions of equation (12) are  $\eta = a_i$ ,  $c_i$  and  $\eta = ta_i + b_i$ ;  $\eta = tc_i + d_i$ , respectively the time-independent and time-dependent solution. So we have four classes of symmetry transformations for the three-dimensional KdV equation. Summarizing our above observations we can comment that we have constructed four classes of generators  $A_i$ ,  $B_i$ ,  $C_i$  and  $D_i$ , which generate the four classes of symmetries. These generators close on an infinite-dimensional Kac-Moody algebra, given by

$$\begin{aligned}
 \llbracket A_n, B_m \rrbracket &= (n)A_{n+m-1} & \llbracket A_n, A_m \rrbracket &= 0 \\
 \llbracket C_n, D_m \rrbracket &= (n)C_{n+m-1} & \llbracket C_n, C_m \rrbracket &= 0 \\
 \llbracket B_m, D_n \rrbracket &= 0 \\
 \llbracket A_m, C_n \rrbracket &= 0 \\
 \llbracket B_n, B_m \rrbracket &= -mB_{n+m-1} \\
 \llbracket D_n, D_m \rrbracket &= -mD_{n+m-1}.
 \end{aligned}$$

So we have proved the existence of an infinite class of symmetries of 3D KdV problems, which is an important condition for the complete integrability of the system.

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